



PS00007254A07

GL20-0032ETN-M Series Digital Output Module User Guide

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www.inovance.com



Preface

■ Introduction

GL20-0032ETN-M series 32-channel digital output expansion module supports output of source type. It can be used with GL20 series communication interface modules and Easy series PLCs.

This guide introduces the product information, mechanical installation, electrical installation, program commissioning, and troubleshooting of the product.

■ Standards Compliance

The following table lists the certifications, directives, and standards that the product may comply with. For details about the acquired certificates, see the certification marks on the product nameplate.

Certification	Directive		Standard
CE Certification	EMC Directive	2014/30/EU	24 VDC products: EN 61131-2 220 VAC products: EN 61131-2 EN 61000-3-2 EN 61000-3-3
	LVD Directive	2014/35/EU	EN 61010-1 EN 61010-2-201
	RoHS Directive	2011/65/EU amended by (EU)2015/863	EN IEC 63000
UL/cUL Certification	-		UL 61010-1 UL 61010-2-201 CAN/CSA-C22.2 No. 61010-1 CSA C22.2 NO. 61010-2-201
KCC Certification	-		-
EAC Certification	-		-

Certification	Directive		Standard
UKCA	Safety Regulations	Electrical Equipment (Safety) Regulations 2016	EN 61010-1 EN 61010-2-201
	EMC Regulations	Electromagnetic Compatibility Regulations 2016	24 VDC products: EN 61131-2 220 VAC products: EN 61131-2 EN 61000-3-2 EN 61000-3-3
	RoHS Regulations	Directive (RoHS) Regulations 2012	EN IEC 63000

■ More Data

Name	Code	Description
GL20-RTU-ECT Series Communication Interface Module User Guide	PS00004985	Introduces the installation, wiring, and other information of the product.
GL20-RTU-PN Series Communication Interface Module User Guide	PS00007594	Introduces the installation, wiring, and other information of the product.
GL20-RTU-ECT32 Series Communication Interface Module User Guide	PS00013434	Introduces the product information, mechanical installation, electrical installation, program commissioning, and troubleshooting of the product.
GL20-0032ETN-M Series Digital Output Module User Guide (This guide)	PS00007254	Introduces the product information, mechanical installation, electrical installation, program commissioning, and troubleshooting of the product.

■ Revision History

Date	Version	Revision
June 2025	A07	Made minor corrections.
July 2024	A06	Updated " 2.1 Installation Precautions " on page 17 .
June 2024	A05	Modified the "Rated current of bus input power supply" of power supply specifications in " 1.3 Technical Specifications " on page 14 .
January 2024	A04	Added: <ul style="list-style-type: none">● Added "2.1 Installation Precautions" on page 17.● Added "Troubleshooting" on page 35.● Added "Appendix: Version Matching Information" on page 37. Modified: <ul style="list-style-type: none">● Modified the component descriptions in "1.2 Components" on page 12.● Modified the operation steps in "Program Commissioning" on page 27.
July 2023	A03	Modified section 3.1.
April 2023	A02	Added: Added general specifications in section 1.3. Modified: <ul style="list-style-type: none">● Modified section 2.2.● Modified section 3.1.
January 2023	A01	Made minor corrections.
January 2023	A00	Initial release.

■ Access to the Guide

This guide is not delivered with the product. You can obtain the PDF version in the following ways

- Do keyword search under Service and Support at www.inovance.com.

- Scan the QR code on the product with your smart phone.
- Scan the QR code below to install My Inovance app, where you can search for and download user guides.



■ Warranty Disclaimer

Inovance provides warranty service within the warranty period (as specified in your order) for any fault or damage that is not caused by improper operation of the user. You will be charged for any repair work after the warranty period expires.

Within the warranty period, maintenance fee will be charged for the following damage:

- Damage caused by operations not following the instructions in the user guide
- Damage caused by fire, flood, or unusual voltage
- Damage caused by unintended use of the product
- Damage caused by use beyond the specified scope of application of the product
- Damage or secondary damage caused by force majeure (natural disaster, earthquake, and lightning strike)

The maintenance is charged according to the latest Price List of Inovance. If otherwise agreed upon, the terms and conditions in the agreement shall prevail.

For details, see Product Warranty Card.

Safety Precautions

■ Safety Disclaimer

1. Read and follow the safety instructions when installing, operating, and maintaining the equipment.
2. To ensure your safety and prevent damage to the equipment, follow the marks on the equipment and all the safety instructions in this guide.
3. "CAUTION", "WARNING", and "DANGER" items in the guide do not indicate all safety precautions that need to be followed; instead, they just supplement the safety precautions.
4. Use this equipment according to the designated environment requirements; otherwise, a fault may occur. Malfunction or damage caused by improper use is not covered by warranty.
5. Inovance shall take no responsibility for any personal injury or property damage caused by improper use.

■ Safety Levels and Definitions



"DANGER" indicates that failure to comply with the notice will result in death or severe personal injuries.



"WARNING" indicates that failure to comply with the notice may result in death or severe personal injuries.



"CAUTION" indicates that failure to comply with the notice may result in minor or moderate personal injury or equipment damage. Keep this user guide properly for future use and deliver it to the end user.

Control System Design



- Provide a safety circuit outside the PLC so that the control system can still work safely once external power failure or controller fault occurs.
- Add a fuse or circuit breaker because the module may smoke or catch fire due to long-time overcurrent caused by operation above rated current or load short-circuit.



- An emergency stop circuit, a protection circuit, a forward/reverse operation interlocked circuit, and an upper position limit and lower position limit interlocked circuit must be set in the external circuits of PLC to prevent damage to the equipment.
- To ensure safe operation, for the output signals that may cause critical accidents, use external protection circuits and safety mechanism.
- Once the CPU of the controller detects an exception in the system, all outputs may be closed. When a fault occurs in the controller circuit, the output may not be under control. Therefore, it is necessary to set up an external control circuit to ensure normal operation.
- If the output units such as relays or transistors are damaged, the output may fail to switch between ON and OFF states according to the commands.
- The PLC is designed to be used in an indoor electrical environment (overvoltage category II). The power supply must have a system-level surge protector, assuring that overvoltage due to lightning shock cannot be applied to the PLC's power supply input terminals, signal input terminals, and output terminals, to prevent damage to the equipment.

Installation



- Installation must be carried out by skilled personal who have undergone specialized electrical training and possess comprehensive electrical expertise.
- Disconnect all external power supplies of the system before disassembling the module. Failure to do so may result in electric shock, module fault, or malfunction.
- Do not use the PLC in environments with dust, greasy smoke, conductive dust, corrosive or combustible gases, exposed to high temperature, condensation, wind & rain, or subject to vibration and shock. Electric shock, fire, and malfunction may also result in damage or deterioration to the product.
- The PLC is open-type equipment that must be installed in a control cabinet with lock (cabinet housing protection > IP20). Only the skilled personnel who have undergone specialized electrical training and possess comprehensive electrical expertise can open the cabinet.



- Ensure there are no unwanted matters on ventilation surface. Failure to comply may result in poor ventilation, which may cause fire, fault, and malfunction.
- Prevent metal filings and wire ends from dropping into ventilation holes of the PLC during installation. Failure to comply may result in fire, fault, and malfunction.
- Ensure the module is connected to the respective connector securely and hook the module firmly. Improper installation may result in malfunction, fault or fall-off.
- Ensure natural ventilation for the equipment.

Wiring



- Wiring must be carried out by skilled personnel who have undergone specialized electrical training and possess comprehensive electrical expertise.
- Disconnect all external power supplies of the system before wiring. Failure to comply may result in electric shock, module fault, or malfunction.
- Install the terminal cover attached to the product before power-on or operation after wiring is done. Failure to comply may result in electric shock.
- Insulate the cable terminals properly to ensure the insulation distance between cables will not be shortened after cables are connected to the terminal block. Failure to comply may result in electric shock or damage to the equipment.

Wiring



- To avoid electric shock, cut off the power supply before connecting the equipment to the power supply.
- The input power supply of this product must be 24 VDC. Power supplies outside $\pm 20\%$ of 24 VDC can cause severe damage to the product. Therefore, check whether the DC power supply provided by the switching-mode power supply is stable at a regular interval.

Operation and Maintenance



- Operation and maintenance must be carried out by skilled personnel who have undergone specialized electrical training and possess comprehensive electrical expertise.
- Do not touch the terminals while the power is on. Failure to comply may result in electric shock or malfunction.
- Disconnect all external power supplies of the system before cleaning the module or re-tightening screws on the terminal block or screws of the connector. Failure to comply may result in electric shock.
- Disconnect all external power supplies of the system before assembling/disassembling the module or connecting/removing the communication cables. Failure to comply may result in electric shock or malfunction.

Safety Recommendations

- In the position where the operator directly touches the machinery part, for example, where a machinery tool is loaded/unloaded, or where a machine runs automatically, the on-site manual operating devices and any other alternative means must be carefully arranged and designed so that they are independent of the PLC and can start or terminate the automatic running of the system.
- If modification on the program is needed during system operation, use the lock function or other protective measures. Ensure that only authorized personnel can make the necessary modifications.

Disposal



- Treat the scrapped product as industrial waste. Dispose of the battery according to local laws and regulations.
- Recycle retired equipment in accordance with industry waste disposal standards to avoid environmental pollution.

1 Product Information

1.1 Naming Rules and Nameplate

GL 20 - 00 32 E TN - M

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① Product Information GL: Inovance general local module	③ Number of Input Channels 00: 0 input channel	⑤ Module Type E: Logic I/O expansion module	⑦ Terminal Type M: Ejector header (For the PUSHIN terminal, this item is empty by default)
② Series Number 20: 20 series module	④ Number of Output Channels 32: 32 output channels	⑥ Output Type TN: Transistor output (sink mode)	-



INOVANCE

GL20-0032ETN-M
32 Digital Output Module

POWER INPUT: DC24V 200mA
OUTPUT: DC24V/0.5A RES. LOAD SN:0123456789123456

QC PASSED

Certification

MANUAL

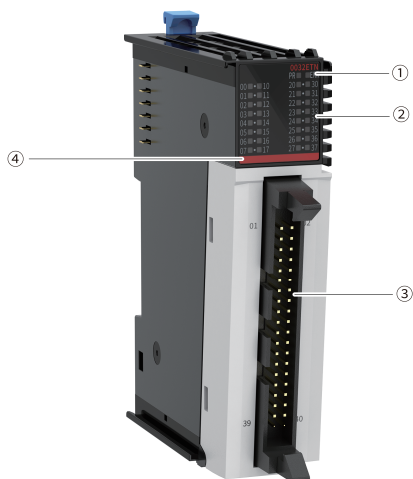
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Suzhou Inovance Technology Co., Ltd. Made in China

The data for ordering the product is shown below.

Model	Description	Material Code	Applicable Model
GL20-0032ETN-M	GL20 series 32-channel transistor NPN output module	01440377	It is applicable to GL20 series communication interface modules and Easy series PLC products.

1.2 Components



No.	Name	Description			
①	Signal indicators	PR (POWER +RUN)	Power/Run indicator	Yellow-green	<ul style="list-style-type: none"> Steady ON: The module is operating normally. Flashing quickly: The module is addressed successfully. Flashing slowly: The module is powered on but not addressed. OFF: The module is not powered on or is faulty.
		ERR	Fault indicator	Red	ON when the module is faulty. For details, see " Troubleshooting " on page 35
②	I/O signal indicator	00 to 37	I/O signal indicator	Yellow-green	Steady ON: The input/output is active. OFF: The input/output is inactive.
③	User terminal	/	0 input and 32 outputs	/	For details, see " 3.2 Terminal Definition " on page 23
④	Color identification		Red: Digital output		Orange: Analog output
			Gray: Digital input		Green: Analog input
			White: Communication		Blue: Other modules

- Flashing quickly: The indicator is on for 200 ms and off for 200 ms.
- Flashing slowly: The indicator is on for 200 ms and off for 1 s.

1.3 Technical Specifications

■ General specifications

Item	Specification
IP rating	IP20
Dimensions (W x H x D)	24 mm x 100 mm x 75 mm
Weight	About 87 g

■ Power supply specifications

Item	Specification
Rated voltage of bus input power supply	5 VDC (4.75 VDC to 5.25 VDC)
Rated current of bus input power supply	85 mA (typical value @5 V)
Rated voltage of terminal input power supply	24 VDC (20.4 VDC to 28.8 VDC)
Rated current of terminal input power supply	100 mA (typical@24 V)
Rated voltage of terminal output power supply	/
Rated current of terminal output power supply	/
Hot swap	Not supported

■ Interface specifications

Item	Specification
Output type	Digital output, low side transistor output
Output mode	Sink mode
Maximum number of output channels	32
Output voltage	24 VDC \pm 10% (21.6 VDC to 26.4 VDC)
Resistive output load	0.5 A/channel; 8 A/module

Item	Specification
Inductive output load	7.2 W/channel; 48 W/module
Lamp output load	5 W/channel; 36 W/module
Hardware response time upon ON/OFF	100 μ s/100 μ s
Leakage current upon OFF	10 μ A
Switching frequency	Resistive load: 100 Hz; inductive load: 0.5 Hz; lamp load: 10 Hz
Isolation	Isolated
Output indicator	The output indicator turns on (controlled by software) when the output is in drive state.
Output derating	The module works at full load at 45°C (with a maximum total current of 8 A for 32 output channels) and works at 50% of full load at 55°C (with a maximum total current of 4 A).
Protective functions	Short circuit protection and overcurrent protection

■ Software specifications

Item	Specification
Output PDO data volume	4 bytes
Programming software version	AutoShop V4.8.1 and above InoProShop V1.7.3 and above
Output state mode during fault stop	Output zero, last value, or preset value
Preset value output during fault stop	0 or 1
Output terminal fault detection and indication	Not supported
Output channel logic level configuration	Not supported
Independent channel enable configuration	Not supported
Diagnostic report function configuration	Not supported

Item	Specification
Output in the stop mode	Outputted based on fault stop state mode and preset value (no longer updated)
I/O mapping	Support bitwise, byte-wise, and word-wise I/O mapping modes

1.4 Environmental Specifications

Item	Specification
Installation/application environment	Free from conductive dust, conductive fibers, explosive dust, flammable gases, water mist/greasy dirt, corrosive dusts/gases, strong vibration, and repetitive shock
Altitude	≤ 2,000 m
Pollution degree	2
Immunity	2 kV on power supply cable (compliant with IEC 61000-4-4)
Overvoltage category	I
EMC immunity level	Zone B, IEC61131-2
Anti-static rating	Contact discharge +/-6 kV and air discharge +/-8 kV
Vibration resistance	<ul style="list-style-type: none"> ● Application scenario: Tested according to IEC60068-2-6, 3.5 mm amplitude from 5 Hz to 8.4 Hz; 1 g acceleration from 8.4 Hz to 200 Hz; 10 cycles per axial direction ● Transportation scenario: Tested according to IEC60068-2-64, 0.01 g²/Hz power spectral density from 5 Hz to 100 Hz; 0.001 g²/Hz power spectral density at 200 Hz; 1.14 g Grms
Shock resistance	Application/Transportation scenario: Tested according to IEC60068-2-27; 15 g peak acceleration, 11 ms pulse width, 18 cycles in total in X, Y and Z axial directions
Operating temperature/humidity	<ul style="list-style-type: none"> ● Temperature: -20°C to +55°C ● Humidity: < 95% RH (30°C), without condensation
Storage temperature/humidity	<ul style="list-style-type: none"> ● Temperature: -20°C to +60°C ● Humidity: < 95% RH (30°C), without condensation
Transportation temperature/humidity	<ul style="list-style-type: none"> ● Temperature: -40°C to +70°C ● Humidity: < 95% RH (40°C), without condensation

2 Mechanical Installation

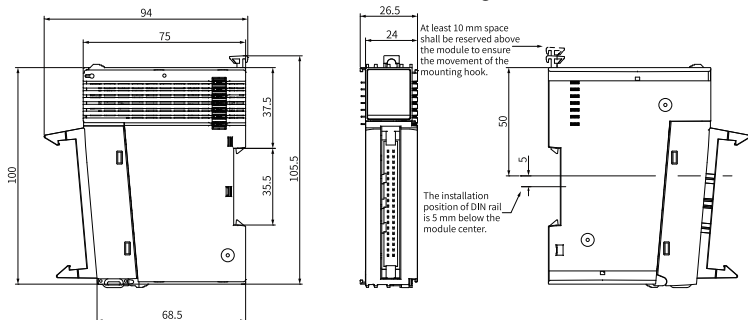
2.1 Installation Precautions

- Make sure the module is powered off before installing or removing.
- Do not hot swap the modules. Otherwise, the modules may be damaged by overcurrent or overvoltage, and the communication interface module or PLC may be subject to restart, user data loss or corruption.
- Do not drop or shock the housing or terminals of the module to avoid damage.

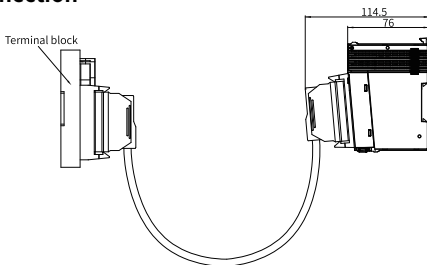
2.2 Installation Dimensions

■ Module

The installation dimensions (in mm) are shown in the figure below.



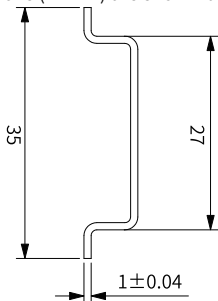
■ Cable connection



2.3 Installation Method

■ Installing modules side by side

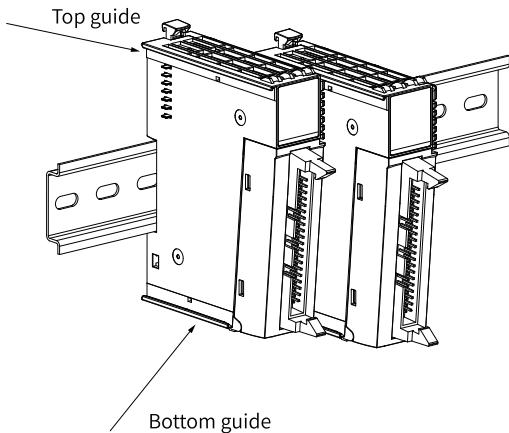
The module is mounted onto a DIN rail according to IEC 60715 (width: 35 mm, thickness: 1 mm). The dimensions (in mm) are shown below.



Caution

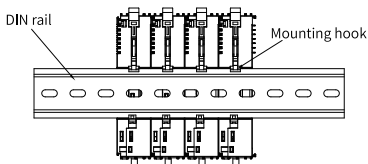
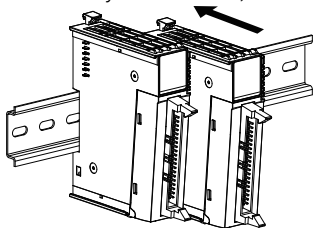
When installed on a DIN rail other than the recommended one (especially the one whose thickness is not 1.0 mm), the module will not fit in place as the mounting hook does not work.

Install modules side by side by sliding them along the top and bottom guide rails of adjacent modules.

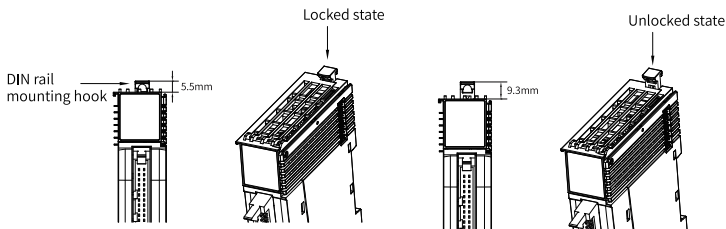


■ Installing modules onto DIN Rail

1. Align the module with the DIN rail and push it in the direction indicated by the arrow until you hear a click, as shown below.



2. Make sure the DIN rail mounting hook of the module is locked. The locked and unlocked states of the mounting hook are shown below.



- If the mounting hook is pressed down, it is locked.
- If the mounting hook is lifted up, it is unlocked.

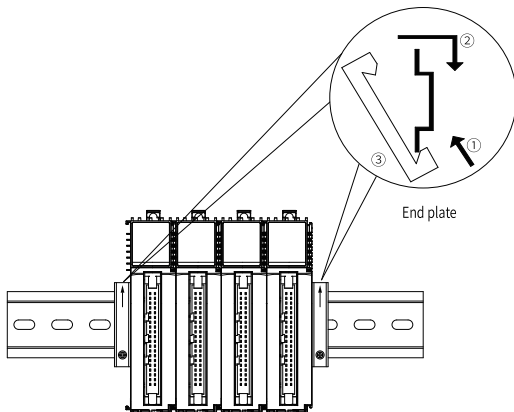
To lock the module to the DIN rail, press down the mounting hook.



Caution

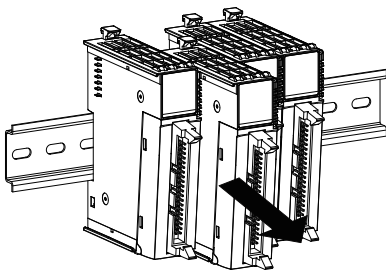
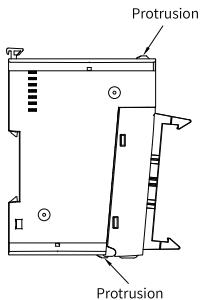
When the module is not installed on the rail, keep the mounting hook in the locked state. Keeping the mounting hook unlocked for a prolonged time may cause the hook to fail.

3. Install a DIN rail end plate on both sides of the PLC or expansion module. To install the end plate, hook the bottom of it to the bottom of the DIN rail, rotate the end plate to hook the top of it to the top of the DIN rail, and then tighten the screw to lock the end plate in place, as shown below.



■ Removing modules

Pry the DIN rail mounting hook upwards with a tool such as slotted screwdriver, hold the protrusions and pull the module out straight forward, and then press down the top of the DIN rail mounting hook.



3 Electrical Installation

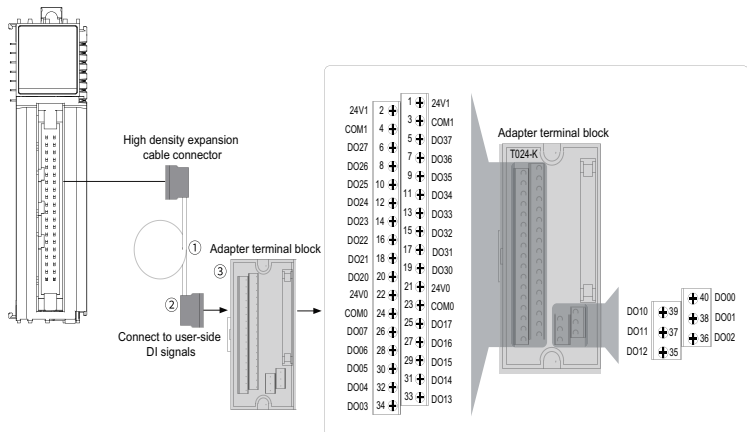
3.1 External Terminal Block and Cable Selection

The following table describes the order data of the terminal block and the cable.

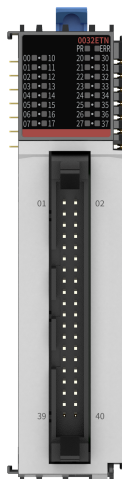
Name	Material Code	Model	Description	Remark
Cable (connector not provided)	15310167	XA3210A-40-L0.5M-01	40PIN MIL cable (500 mm)	High density adapter cable, including two 40PIN MIL connectors (500 mm)
	15310166	XA3210A-40-L2M-01	40PIN MIL cable (2000 mm)	High density adapter cable, including two 40PIN MIL connectors (2000 mm)
Terminal block	15020452	T024-K	40PIN MIL-to-screw terminal block	T024-K

■ Terminal block connection

After installation, connect the module to the external I/O terminal block through connecting cables. This module supports one external terminal block. When the T024-K adapter terminal block is used for connection, the correspondence between the terminals of the block and the terminals of the module is shown in the figure below. (When other types of adapter terminal blocks are used, check the terminal correspondence.)



3.2 Terminal Definition



Left Indicator	Left Signal	Left Terminal	Right Terminal	Right Signal	Right Indicator
/	24V1	01	02	24V1	/
/	COM1	03	04	COM1	/
37	DO37	05	06	DO27	27
36	DO36	07	08	DO26	26
35	DO35	09	10	DO25	25
34	DO34	11	12	DO24	24
33	DO33	13	14	DO23	23
32	DO32	15	16	DO22	22
31	DO31	17	18	DO21	21
30	DO30	19	20	DO20	20
/	24V0	21	22	24V0	/
/	COM0	23	24	COM0	/
17	DO17	25	26	DO07	07
16	DO16	27	28	DO06	06
15	DO15	29	30	DO05	05
14	DO14	31	32	DO04	04
13	DO13	33	34	DO03	03
12	DO12	35	36	DO02	02
11	DO11	37	38	DO01	01
10	DO10	39	40	DO00	00

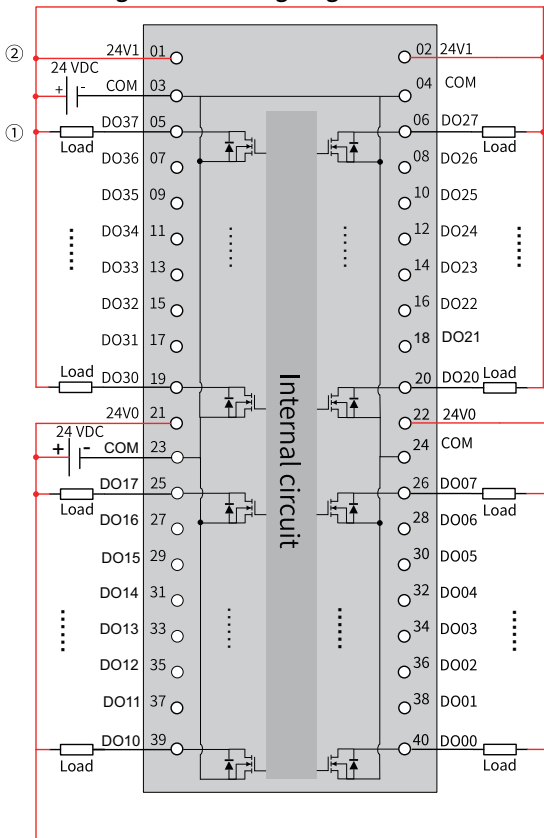
3.3 Terminal Wiring

■ Wiring precautions

- Do not bundle the expansion cable together with power cables (with high voltage and large current) that produce strong interference signals; otherwise, the expansion cable may be influenced by noise, surge, and induction. Separate it from other cables and avoid cabling in parallel.
- Use recommended cables and adapter boards for connection. It is recommended that shielded cables be used as expansion cables to enhance anti-interference capacity.

- Apply single-point grounding for the shielding of shielded cable and solder sealed cable.

■ Circuit block diagram and wiring diagram



No.	Description
①	Terminals 05 to 19, 06 to 20, 25 to 39, and 26 to 40 are output terminals for wiring.
②	Terminals 01, 03, 21, 23, 02, 04, 22, and 24 are power supply terminals for wiring.



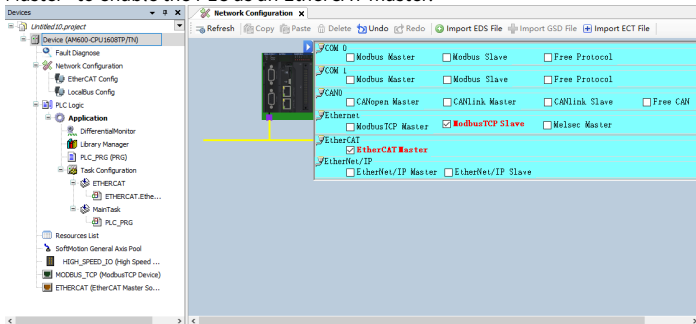
Caution

It is recommended to add one COM connection for every additional 8 output channels to enhance the current-carrying capacity.

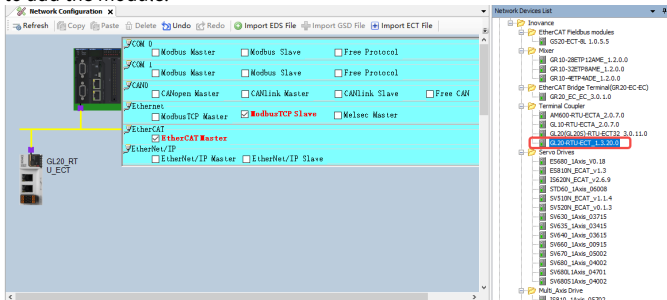
4 Program Commissioning

In the programming software interface, the GL20-0032ETN-M module is displayed as "GL20-0032ETN". The following is an example where AM600 is used as the master control module along with the GL20-0032ETN-M module.

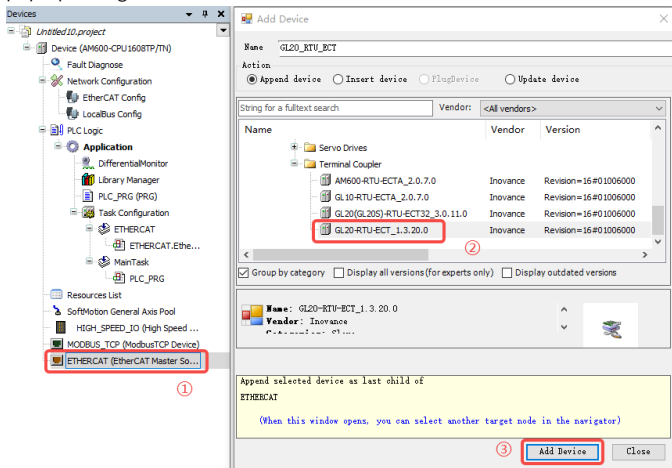
1. Enable the AM600 PLC as the EtherCAT master and add the GL20-RTU-ECT communication interface module.
 - a. In the left **Devices** pane, double-click **Network Configuration** and click the AM600 PLC figure in the upper left corner of the interface. Check the "EtherCAT Master" to enable the PLC as an EtherCAT master.



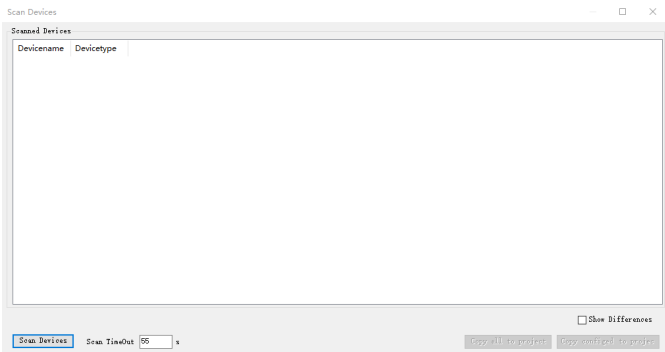
- b. Add the GL20-RTU-ECT communication interface module.
 - Method 1: In the right **Network Devices List**, double-click "GL20-RTU-ECT" to add the module.



- Method 2: In the left **Devices** pane, right-click **ETHERCAT(EtherCAT Master SoftMotion)** and select **Add Device**. Select "GL20_RTU_ECT_x.x.x.x" in the pop-up dialog box and click **Add Device**.

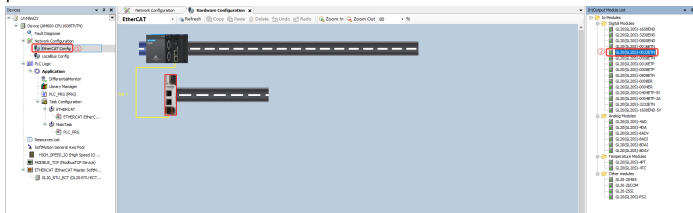


- Method 3: In the left **Devices** pane, right-click **ETHERCAT(EtherCAT Master SoftMotion)** and select **Scan For Devices**. Click **Scan Devices**, select the GL20-RTU-ECT module, and click **Copy Scan Device**.

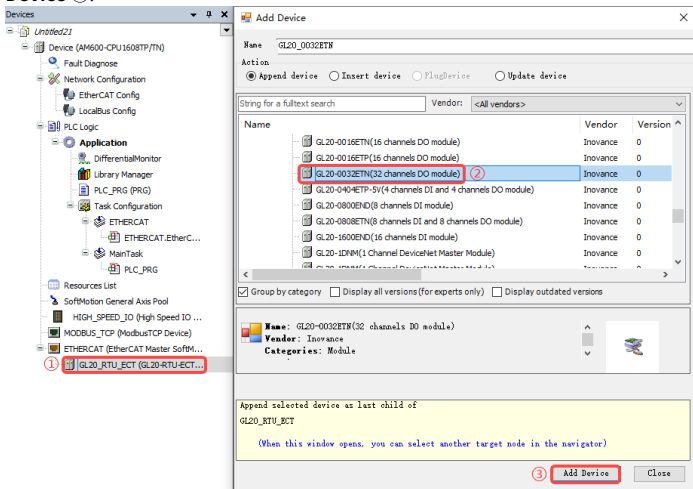


2. Add the GL20-0032ETN-M module.

- Method 1: Open the **Hardware Configuration** pane by double-clicking **EtherCAT Config** ① in the left **Devices** pane, or double-clicking the GL20-RTU-ECT figure in the **Network Configuration** pane. In the right **In/Output Module List**, double-click "GL20-0032ETN" ② or drag the GL20-0032ETN module and place it after the GL20-RTU-ECT module.



- Method 2: In the left **Devices** pane, right-click "GL20_RTU_ECT" ① and select **Add Device**. Select "GL20-0032ETN" ② in the pop-up dialog box and click **Add Device** ③.



- Method 3: In the left **Devices** pane, right-click **ETHERCAT(EtherCAT Master SoftMotion)** and select **Scan For Devices**. Click **Scan Devices**, select the GL20-0032ETN-M module, and click **Copy Scan Device**.

3. Double-click the GL20-0032ETN-M module ① to set the **Channels Config** ②.


The screenshot shows the 'Channels Config' window for the GL20-0032ETN-M module. The window is divided into three sections, one for each channel (0, 1, and 2). Each section contains the following configuration options:

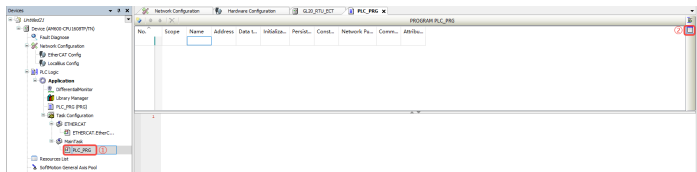
- Out Status after stop or disconnection - Channel X** (where X is 0, 1, or 2):
 - Output last value
 - Output preset value
 - Bitwise setting
- Preset value:** A table with 8 columns (Group 0-7) and 1 row (I). All cells contain 'FALSE'.

The parameters for channel configuration are shown in the following table.

Name	Description	Configuration
Out status after stop or disconnection	Output mode of the output channel of the module in non-OP state (when the module is stopped or the coupler is disconnected)	<p>The following options are supported:</p> <ul style="list-style-type: none"> ● Output last value: All channels in the corresponding group retain the output state before module stop or network disconnection. ● Output preset value: The output mode of each channel in the corresponding group matches the preset values. The preset value is matched by bit, with one bit representing one channel. For example, if bit0 is set to FALSE, the output state of channel 0 is 0; if bit0 is set to TRUE, the output state of channel 0 is 1. ● Bitwise setting: The output mode of each channel in the corresponding group is matched by bit, with one bit representing one channel. For example, bit0 represents channel 0. If bit0 is set to TRUE, channel 0 outputs according to its preset value. If bit0 is set to FALSE, channel 0 retains the last output state.

4. Create output variables.

- a. In the left **Devices** pane, double-click **PLC_PRG** ① and click  ② in the upper right corner to switch to table mode.




- b. Add custom output variables "GL20_CHO0", "GL20_CHO1", "GL20_CHO2", and "GL20_CHO3". Set the scope of these variables to "VAR" and data type to "BYTE", as shown below.

No.	Scope	Name	Address	Data t...	Initializa...	Persist...	Const...	Network Pu...	Comm...	Attribu...
1	VAR	GL20_CHO3		USINT		<input type="checkbox"/>	<input type="checkbox"/>	Default		
2	VAR	GL20_CHO2		USINT		<input type="checkbox"/>	<input type="checkbox"/>	Default		
3	VAR	GL20_CHO1		USINT		<input type="checkbox"/>	<input type="checkbox"/>	Default		
4	VAR	GL20_CH00		USINT		<input type="checkbox"/>	<input type="checkbox"/>	Default		

5. Map the output variables to the corresponding output channel.

- a. In the left **Devices** pane, double-click **GL20_RTU_ECT** ① and click the **EtherCAT I/O Mapping** tab ②.

The screenshot shows the 'Devices' pane on the left with a tree view. The 'GL20_RTU_ECT (GL20-RTU-ECT...)' entry is selected and highlighted with a red box and circled with ①. The main window displays the 'EtherCAT I/O Mapping' tab, which is also highlighted with a red box and circled with ②. This tab contains a table with columns for Variable, Mapping, Channel, Address, Type, Default Value, Unit, and Description. The table lists several variables like %QW1, %Q84, %Q85, %Q86, %Q87, %Q88, %NW2, %NW3, %NW4, %NW5, %NW6, %NW7, %NW8, %NW9, %NW10, %NW11, %NW12, %NW13, %NW14, %NW15, %NW16, %NW17, %NW18, %NW19, %NW20, %NW21, %NW22, %NW23, %NW24, %NW25, %NW26, %NW27, %NW28, %NW29, %NW30, %NW31, %NW32, %NW33, %NW34, %NW35, %NW36, %NW37, %NW38, %NW39, %NW40, %NW41, %NW42, %NW43, %NW44, %NW45, %NW46, %NW47, %NW48, %NW49, %NW50, %NW51, %NW52, %NW53, %NW54, %NW55, %NW56, %NW57, %NW58, %NW59, %NW60, %NW61, %NW62, %NW63, %NW64, %NW65, %NW66, %NW67, %NW68, %NW69, %NW70, %NW71, %NW72, %NW73, %NW74, %NW75, %NW76, %NW77, %NW78, %NW79, %NW80, %NW81, %NW82, %NW83, %NW84, %NW85, %NW86, %NW87, %NW88, %NW89, %NW90, %NW91, %NW92, %NW93, %NW94, %NW95, %NW96, %NW97, %NW98, %NW99, %NW100, %NW101, %NW102, %NW103, %NW104, %NW105, %NW106, %NW107, %NW108, %NW109, %NW110, %NW111, %NW112, %NW113, %NW114, %NW115, %NW116, %NW117, %NW118, %NW119, %NW120, %NW121, %NW122, %NW123, %NW124, %NW125, %NW126, %NW127, %NW128, %NW129, %NW130, 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- b. On the **EtherCAT I/O Mapping** tab, double-click a variable entry and click  ① to open the **Input Assistant** dialog box. Choose **Application > PLC_PRG >** specific variables ② and click **OK**

General Find Filter Show all Set Continuous Address

Variable	Mapping	Channel	Address	Type	Default Value	Unit	Description
LC_PRG.GL20_CHO0		Device control	%QW1	UINT			Device control
GL20_0032ET...		GL20_0032ET...	%QB4	USINT			GL20_0032ET...

Input Assistant

Text Search Categories

Name	Type	Address
Application	Application	
PLC_PRG	PROGRAM	
GL20_CHO0	USINT	
GL20_CHO1	USINT	
GL20_CHO2	USINT	
GL20_CHO3	USINT	
IoConfig_Globals	VAR_GLOBAL	
SMEElement		
SDElement		
SM3_Basic	Library	SM3_Basic, 4.10.9.0 (3)
SM3_Math	Library	SM3_Math, 4.10.0.0 (3)
SM3_CNC	Library	SM3_CNC, 4.2.1.1 (3)
IoDrvEthercatLib	Library	IODrvEtherCAT, 3.5.11.5

Structured view Filter None

Documentation
GL20_CHO0: USINT(VAR)

Messages - Total 0 error(s), 0 warning(s), 0 message(s)

OK Cancel


Map the output variables "GL20_CHO0", "GL20_CHO1", "GL20_CHO2", and "GL20_CHO3" to the output channels of the configured module.




General Find Filter Show all Add FB for IO Channel... Go to Instance

Variable	Channel	Address	Type	Default Value	Unit	Description
Application.POU.GL20_0032_OUT0	GL20_0032ETN Digital output CH0-8bit	%QB4	USINT			GL20_0032ETN Digital output CH0-8bit
Application.POU.GL20_0032_OUT1	GL20_0032ETN Digital output CH1-8bit	%QB5	USINT			GL20_0032ETN Digital output CH1-8bit
Application.POU.GL20_0032_OUT2	GL20_0032ETN Digital output CH2-8bit	%QB7	USINT			GL20_0032ETN Digital output CH2-8bit
Application.POU.GL20_0032_OUT3	GL20_0032ETN Digital output CH3-8bit	%QB7	USINT			GL20_0032ETN Digital output CH3-8bit
	Libus status	%QW10	UINT			Libus status
	Fault ID	%QW11	UINT			Fault ID

6. Double-click **PLC_PRG** in the left **Devices** pane and complete the programming on the **PLC_PRG** page.

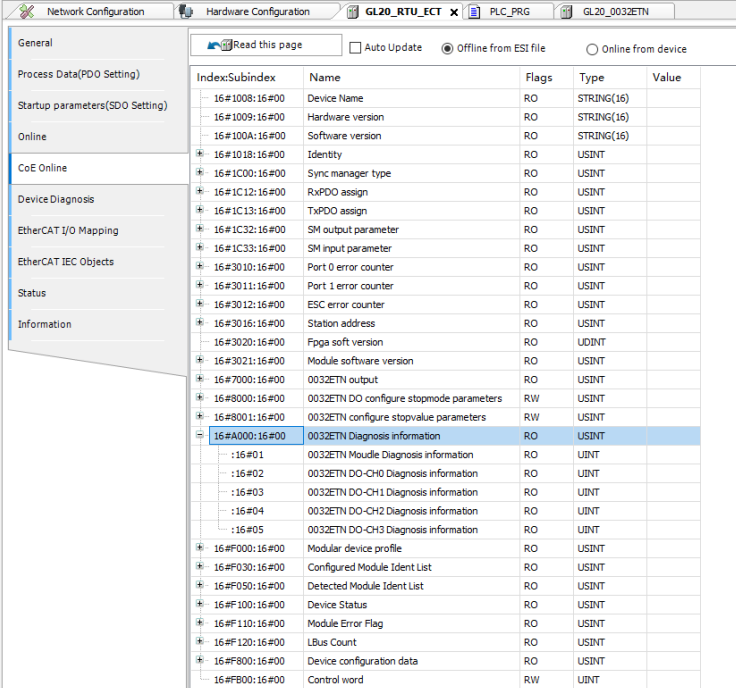
7. Check, compile, log in, download, and run the program.

a. Click  on the toolbar at the top of the interface to check whether the program is correct.

- b. Click  on the toolbar to compile all the code into PLC executable code.
- c. Click  on the toolbar, and follow the interface prompts to log in to the PLC and download the program.
- d. Click  on the toolbar to execute the program.

5 Troubleshooting

When the ERR indicator is ON, the module is faulty. The module reports a fault code. You can get the fault code through the diagnostic data object dictionary value displayed on the **CoE Online** interface, as shown below. For the module installed in slot n ($n = 0$ to 31), the object dictionary definition for index $0xA000+0x40*n$ is shown in the table below.



Index:Subindex	Name	Flags	Type	Value
16#1008:16#00	Device Name	RO	STRING(16)	
16#1009:16#00	Hardware version	RO	STRING(16)	
16#100A:16#00	Software version	RO	STRING(16)	
16#1018:16#00	Identity	RO	USINT	
16#1C00:16#00	Sync manager type	RO	USINT	
16#1C12:16#00	RxPDO assign	RO	USINT	
16#1C13:16#00	TxPDO assign	RO	USINT	
16#1C32:16#00	SM output parameter	RO	USINT	
16#1C33:16#00	SM input parameter	RO	USINT	
16#3010:16#00	Port 0 error counter	RO	USINT	
16#3011:16#00	Port 1 error counter	RO	USINT	
16#3012:16#00	ESC error counter	RO	USINT	
16#3016:16#00	Station address	RO	USINT	
16#3020:16#00	Fpga soft version	RO	UDINT	
16#3021:16#00	Module software version	RO	USINT	
16#7000:16#00	0032ETN output	RO	USINT	
16#8000:16#00	0032ETN DO configure stopmode parameters	RW	USINT	
16#8001:16#00	0032ETN configure stopvalue parameters	RW	USINT	
16#A000:16#00	0032ETN Diagnosis information	RO	USINT	
:16#01	0032ETN Module Diagnosis information	RO	UINT	
:16#02	0032ETN DO-CH0 Diagnosis information	RO	UINT	
:16#03	0032ETN DO-CH1 Diagnosis information	RO	UINT	
:16#04	0032ETN DO-CH2 Diagnosis information	RO	UINT	
:16#05	0032ETN DO-CH3 Diagnosis information	RO	UINT	
16#F000:16#00	Modular device profile	RO	USINT	
16#F030:16#00	Configured Module Ident List	RO	USINT	
16#F050:16#00	Detected Module Ident List	RO	USINT	
16#F100:16#00	Device Status	RO	USINT	
16#F110:16#00	Module Error Flag	RO	USINT	
16#F120:16#00	LBUS Count	RO	USINT	
16#F800:16#00	Device configuration data	RO	USINT	
16#FB00:16#00	Control word	RW	UINT	

- Diagnostic data

For the module in slot n ($n = 0$ to 31), the object dictionary definition for index $0xA000+0x40*n$ is shown in the table below.

Index	0xA000+0x40*n: 0032ETN Diag data				
Subindex	Name	Data Type	Access Mode	Mapping	Default Value
0	Subindex 000	USINT	RO	NO	5
1	Module Error Code	UINT	RO	NO	0x0000
2	DO Channel Error Code CH0	UINT	RO	NO	0x0000
3	DO Channel Error Code CH1	UINT	RO	NO	0x0000
4	DO Channel Error Code CH2	UINT	RO	NO	0x0000
5	DO Channel Error Code CH3	UINT	RO	NO	0x0000

- Fault code

Code	Description	Solution
0x5003	External 24 V power failure	Check the isolated power supply of the module.

Note

Fault detection is only supported for the output power supply of the GL20-0032ETN-M module. When the output power supply is faulty (undervoltage), the diagnostic code is 0x5003.

6 Appendix: Version Matching Information

Contact Inovance technical support to obtain the firmware of GL20-0032ETN-M module and the firmware of communication interface module. XML files and the AutoShop/InoProShop software can be downloaded from the software and debugging tools tab on the GL20 series product page at <https://www.inovance.com>. The following table describes the version matching information.

■ Locally adapted versions

Product Name	Board Software Version	Logic Software/ Programming Software Version	XML/GSD File Version
Local module	-	0.1.2.0 and above	-
Easy series PLC	V6.1.0.1 and above	AutoShop: V4.8.2.3 and above	-
AM300/AM500 series PLC	V1.2.0.0 and above	InoProShop: V1.7.3 SP6 and above	-

■ Remotely adapted versions

Product Name	Board Software Version	Logic Software/ Programming Software Version	XML/GSD File Version
Local module	-	0.1.2.0 and above	-
GL20-RTU-ECT	2.4.13.0 and above	0.1.3.2 and above	1.3.9.0 and above
GL20-RTU-ECT32	2.5.9.0 and above	0.1.4.2 and above	16 and 32_3.0.4.0 and above
GL20-RTU-PN	2.1.1.0 and above	-	20230323 and above
Easy series PLC	V6.1.0.1 and above	AutoShop: V4.8.2.3 and above	-
AM300/AM500 series PLC	V1.2.0.0 and above	InoProShop: V1.7.3 SP6 and above	-
AM780 series PLC	V1.10.0.0 and above	InoProShop: V1.7.3 SP4 and above	-